Tom Marty

Github
 Git

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in LinkedIn

Montreal, Canada 🎔 Twitter

Ph.D. in Machine Learning	Jan. 2024 –
MILA - Montréal Institute of Learning Algorithms - GPA 4.00	Montréal, Canada
M.Sc. in Machine Learning Polytechnique Montréal - GPA 3.91	Sep. 2021 – Jun. 2023 Montréal, Canada
B.Sc. in Computer Science, minor in Applied Mathematics X 2018, Ecole Polytechnique - GPA 3.84	Sep. 2018 – Jun. 2021 Palaiseau, France
Lycée Jean-Baptiste Say "Classe préparatoire" Intensive multi-disciplinary preparation - GPA 4.00 - Top 0.1% national	Sep. 2016 – Jun. 2018 l Paris, France

Research Interest

EDUCATION

- Broad interest : Artificial intelligence, Machine Learning, Generative AI and Operational Research
- Methodological interest : Causality, Bayesian Statistics, OOD Generalization, Information Theory
- Applications : Fairness, Robust Machine Learning, Open-Ended Decision Making, AI for video-games

INDUSTRY AND ACADEMIC EXPERIENCE

 Visiting Researcher ServiceNow Research Developped WorkArena (ICML2024): an open-source Benchmark and Gym environmer solving common-knowledge tasks on a Web Browser 	Apr. 2023 – Sept. 2023 Montréal, Canada at for evaluating Agent at
 Research Supervisor Corail Research Group Supervised five interns on the development of the open-source project SeaPearl Teaching Assistant for the course INF8215 given by Quentin Cappart in Fall 21 and Fa 	Jan. 2022 – Sept. 2022 Montréal, Canada
 Research Engineer Intern Corail Research Group Developped SeaPearl : an open-source RL-driven generic Constraint Programming solv Used Deep Q-networks and Heterogeneous GNNs to approximate optimal decision procession 	
 Software Engineer Intern Dronisos, drone light show company Developed Harmony, a Physics based meta-heuristic that secures massive drone swarms Harmony - currently in use - reduced the allocated securing time from 2 weeks (handmetametametametametametametametametameta	ade) to 2 seconds

PUBLICATIONS

In-Context Learning and Occam's Razor Eric Elmoznino*, Tom Marty*, Tejas Kasetty, Leo Gagnon, Sarthak Mittal, Mahan Fathi, Dhanya Sridhar, Guillaume Lajoie *under review Code ▷ PDF

Learning a Generic Value-Selection Heuristic Inside a Constraint Programming Solver Tom Marty^{*}, Tristan François, Pierre Tessier, Louis Gautier, Léo-Boisvert, Louis-Martin Rousseau, Quentin Cappart (extended version) *under review

The Unsolved Challenges of LLMs as Generalist Web Agents: A Case Study Rim Assouel^{*}, Tom Marty^{*}, Massimo Caccia, Issam H. Laradji, Alexandre Drouin, Sai Rajeswar, Hector Palacios, Quentin Cappart, David Vazquez, Nicolas Chapados, Maxime Gasse, Alexandre Lacoste Foundation Models for Decision Making Workshop (NeurIPS). 2023.

Tom Marty [*] , Tristan François, Pierre Tessier, Louis Gautier, Louis-Martin Rouss Constraint Programming (CP). 2023.	eau, Quentin Cappart ≮ Code
Other Projects	
On the Necessity of Human Insight and Causality to Improve Adversarial Robu • Work in progress	ustness Mar. 2024 –
 BrowserGym : an Open-Source Benchmark for evaluating Web Agents Python Paper accepted at ICML 2024 Vienna, presented at NVIDIA GTC 2024 	Apr. 2023 – Mar. 2024
SeaPearl : an Open-Source RL-driven Constraint-Programming Solver Julia • Paper accepted at CP2023, Toronto	Fev. 2021 – Jul. 2023
 Adversarial Attacks on Sentiment Classification models Python, HuggingFace Adversarial fine-tunning on large NLP models : Eleuther AI GPT 125M/1.3B/2.7B/6. Evidence of a correlation between scaling and robustness against increasingly subtle A 	-
 Diffusion Geodesic distance for non-linear dimensionality reduction Python Approximated the geodesic distance using a diffusion process over the manifold Proposed a new data visualization algorithm based on Multi-Dimentionnal Scaling and 	Oct. 2021 – Jan. 2022 d Diffusion Geodesic
 Autonomous Drone Swarm Deployment - DGA contest Python, PyTorch Multi-agent Q-Learning method for deployment optimization Density-Based Spatial Clustering for point of interest detection 	Nov. 2020 – Mar. 2021
 Realtime 3D Deep Motion Capture C++, OpenCV, PyTorch Implemented a method of inferring a full character's 3d pose using only a camera as a Inspired by a EECV 2020 research paper to implement the algorithm 	Oct. 2020 – Dec. 2020 n input
 Sketch-based Shape Retrieval Python, C++, OpenGL Implemented a method to find any specific 3d model in a database using a drawing as Succeeded to faithfully retrieve several simple 3D shapes by using a single drawing give 	-
Visit $\boldsymbol{\mathscr{O}}$ my website to delve into these projects	
Honors and Awards	
Distinguished Paper Award at CP2023, Toronto	Sept. 2023
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Distinguished Paper Award at CP2023, Toronto	Sept. 2023
MITACS Accelerate scholarship of two units for my internship at ServiceNow Research	Mar. 2023
Oustanding Investment Mention, Ecole Polytechnique de Paris	Jul. 2022
Vallet Fondation scholarships for outstanding CPGE students	2018

Teaching Assistant	Fall 2022
INF8215, Artificial Intelligence : Algorithms and methods	
Teaching Assistant	Fall 2021
INF8215, Artificial Intelligence : Algorithms and methods	
Teaching Assistant	Nov. 2018 – Mar. 2019
Ministry of National Education	France
• Responsible for a group of up to 20 undergraduate students during scientific workshops	
• Worked alongside the academic team to prepare students for entrance exams	
Reviewing and Community service	
Reviewer: NeurIPS2024 CALM Workshop, MAIS2024, HRAIM 2024	2024
Reviewer: Constraint Programming — $CP2023$	2023
STUDENT ASSOCIATION	
Public Speaking Club: Rethorix	Oct. 2019 – Oct. 2020
• Organization of an eloquence contest between the schools of the Plateau de Saclay	
President of Nuit du Styx	Nov. 2020
• General organization and logistic of an electronic music festival gathering more than 20	00 peoples

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Languages: French : Native | English : Fluent | Russian : Primary Developer Toolbox: Git, Pytorch, Lightning, Hydra, WandB, VScode, SLURM, CI testing Programming Languages: Python, Julia, C++, R

Remote Controlled UAV: Conception, Building, Programmation, Testing, Adjustment **Activities**: Outdoor climbing, river surf, ski, montain hiking

Reference

Prof. Dhanya Sridhar (Ph.D. advisor) Assistant Professor at UdeM, Core academic member at MILA - AI CIFAR Chair holder Email : dhanya.sridhar@mila.quebec

Dr. Alexandre Lacoste

Staff Research Engineer, ServiceNow Research Email : alexandre.lacoste@servicenow.com

Prof. Quentin Cappart (M.Sc. advisor) Assistant Professor at Polytechnique Montréal Email : quentin.cappart@polymtl.ca